ULS ROBOTICS
BES-Ultra

Whole-body drive exoskeleton robot



BES-Ultra

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Product introduction

The Belt-drive Exoskeleton System (BES-UItra) is a whole-body exoskeleton derived from ULSrobotics' professional products. It is designed to enable universities, R&D institutions and medical research centers to conduct further development and research.

The BES-Ultra utilizes ULSrobotics' independently developed intelligent digital drives, integrated modular deceleration system, and adaptive motion control. Combined with ULSrobotics' proprietary software impedance, self-learning gait, and AI motion algorithms and pattern recognition, it achieves high performance. The product features a lightweight and modular design that is interchangeable with lumbar exoskeletons. It also includes a flexible 32-channel plantar pressure sensor array, independent hip and knee joint position sensors of at least 16 bit, and visualized leg length adjustment. The BES-Ultra provides developers with a high-performance, cutting-edge exoskeleton solution.

- Servo power unit
- Force impedance control technology
- Force control integration drive unit
- ULSrobotics's integrated
 TBG (Twist Belt Gear)
 deceleration system



- Flexible plantar pressure sensing array with two feet and 32 channels
- Long-term lithium battery management system
- Exoskeleton IoT motion data platform
- HMI highly matched adjustable mechanism and visual rapid height adjustment module

Cutting-edge system architecture for exoskeleton software

Supports applications in human augmentation, assisted walking and medical research.

Embedded system architecture									
API SDK Function package	Customiz- able gait curve	Non-gait curve	Adaptive force following gait	Force impedance control assistance software package	Position mode control	Torque mode control	Continuous PVT motion control	adjustment of motor controller for hip and knee joints	Phase calibration, etc.
Software language	Unity (C#)		,	VS (C#, JAVA)		MicroPython		MATLAB	
Communica- tion system	CAN (CANOPEN)	Ethernet	TCP/UDP	WIFI	UART	USB 4G IoT		оТ	
Hardware bottom layer	Support EMG			Support OpenI		BCI Supp		port Leap Motion	
	Support scalable RTOS			ARM-based hardware		driver Lib		BSP	
	Motor drive sens		exible force nsing array system	Double coding position feedback system		Digital man-machine interaction interface		Scalable CAN LAN	



WHOLE-BODY DRIVE EXOSKELETON ROBOT

ULS ROBOTICS - BES-Ultra









Burden Assistance Walking assistance

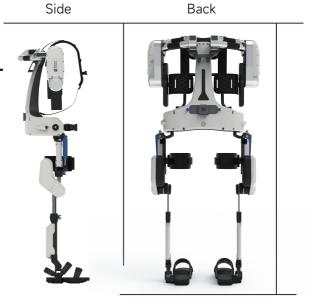
Data IoT

Battery life 3-4h

32 channels for plantar pressure

Equipment weight <25kg

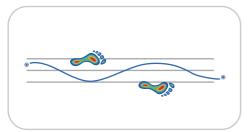
16 degrees of freedom



Supports diverse applications and development functions

ULSrobotics's unique mechanical impedance software algorithm, self-learning adaptive standard gait, non-standard gait and AI-based motion control algorithm and pattern recognition

Development function







Customizable gait curve

Adaptive force following gait

Force impedance control assistance software package





Torque mode control

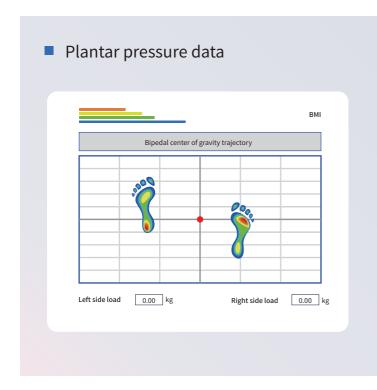
Continuous PVT motion control

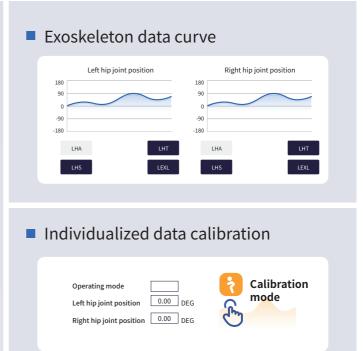
PID adjustment of motor controller for hip and knee joints

Open data and a rich suite of development APIs

The exoskeleton communicates wirelessly to display posture and assistance data in real time, enabling customized data calibration.

Data function



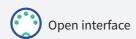


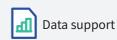
Human-machine integration makes an optimal teaching aid for exoskeleton

Advantages











gait

distribution

Application field



Powerful equipment technical parameters to meet your application requirements



Whole-body exoskeleton robots/**product specification**ULS ROBOTICS **BES-Ultra**

Equipment weight	<25kg (including 1 power battery)				
Working time	3-4 h/battery				
Battery type	Lithium battery 20~42v				
Height range	160~185cm (support height adjustment)				
Standard software	Motion control software, embedded system software, real-time discrete bus system software				
Plantar pressure	32-channel plantar pressure data support				
Degree of freedom	16 Degrees of Freedom Ontology, 8 Active Degrees o Freedom, 8 Passive Degrees of Freedom				
Driving unit	Drive and control integrated low-voltage torque servo motor system, integrated gearbox				

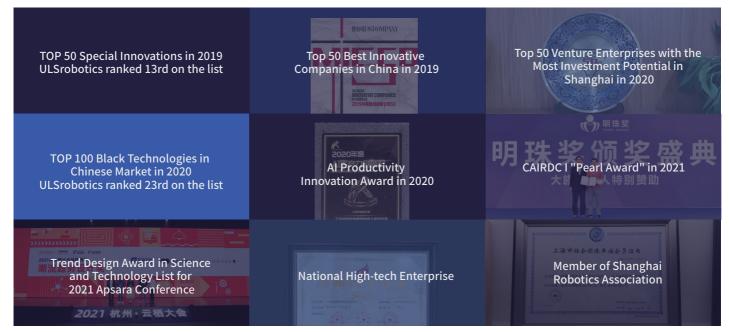


Company profile

ULSrobotics, founded in 2018 and headquartered in Science Park of Shanghai University of Financeand Economics, Shanghai, China, is a high-tech company based on robotics exoskeleton technology platform. ULSrobotics is dedicated in developing, manufacturing and supporting solutions for industrial, medical and educational fields with exoskeleton robots.

ULSrobotics' core R&D team is one of the earliest companies in the world to engage in exoskeleton robotics research and development, with rich experience in designing and developing robot control systems, motion-control algorithms, multi-sensor data fusion, human-computer interaction and machine vision, etc. ULSrobotics' exoskeleton product line covers upper limb, waist, lower limb and whole body, etc. The products have obtained ISO9001 quality certification and CE safety certification. Till now, ULSrobotics has a wealth of application scenarios, such as automobile manufacturing, aviation ground services, electric power, mining and educational research.

Enterprise honor







EMPOWER HUMAN BEING INFINITE

